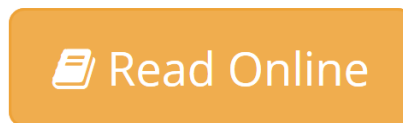


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- humanoid robots,
- robotics hands,
- mobile robots,
- parallel manipulators, and
- human-centred robots.

A good control strategy requires good mechanical design, so a chapter has also been devoted to the description of suitable methods for control architecture design.

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Editorial Review

From the Back Cover

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About the Author

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